## **Differential Geometry and Soliton Dynamics**

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- Homotopy theory
- Ginzburg-Landau vortices
- Vortices at critical coupling and the vortex moduli space
- Relativistic vortex dynamics
- First order vortex dynamics
- Vortices in different geometries

# The Fundamental group $\pi_1(M)$

• Given a manifold M and an interval I = [0, 1] we can define *paths* 

$$\alpha: I \to M: t \mapsto \alpha(t), \text{ where } \alpha(0) = p_0, \ \alpha(1) = p_1.$$

- A loop is a path with  $p_0 = p_1$ .
- Paths can be multiplied via

- The constant path is  $c(s) = p_0$  for all  $s \in I$ .
- The inverse of a paths is  $\alpha^{-1}(s) = \alpha(1-s)$ .
- This is not a group, yet!

## The Fundamental group II

#### Homotopy

Let  $\alpha, \beta: I \to M$  be loops at  $p_0$ .

 $\alpha$  and  $\beta$  are *homotopic*,  $\alpha \sim \beta$ , it there exists a continuous map  $F: I \times I \to M$  such that

•  $F(s,0) = \alpha(s)$  and  $F(s,1) = \beta(s)$  for all  $s \in I$ .

• 
$$F(0,t) = F(1,t) = p_0$$
 for all  $t \in I$ .

- $\alpha \sim \beta$  is an equivalence relation.
- Let  $[\alpha]$  be the equivalence class given by  $\alpha$ .
- Define a product on equivalence classes by [α] \* [β] = [α \* β].
- This gives the fundamental group  $\pi_1(M, p_0)$ .<sup>1</sup>
- Examples:  $\pi_1(S^1) = \mathbb{Z}, \quad \pi_1(\mathbb{R}^2 \setminus \{0\}) = \mathbb{Z}, \quad \pi_1(T^2) = \mathbb{Z} \oplus \mathbb{Z}.$
- Note  $\pi_1(M \times N) = \pi_1(M) \oplus \pi_1(N)$ .

<sup>1</sup>If *M* is arcwise connected then  $\pi_1(M, p_0)$  is isomorphic to  $\pi_1(M, p_1)$ .

 This generalizes naturally to higher homotopy groups: Consider maps from the cube I<sup>n</sup> = I ×···× I to a manifold M such that all the points on the boundary ∂I<sup>n</sup> of the cube are mapped to p<sub>0</sub> ∈ M:

$$\alpha: (I^n, \partial I^n) \to (M, p_0).$$

- Again we can form the product  $\alpha * \beta$  and define the equivalence classes [ $\alpha$ ] (also known as homotopy classes).
- This gives us the *n*th homotopy group  $\pi_n(M)$ .
- Homotopy groups are Abelian for n > 1, i.e  $[\alpha] * [\beta] = [\beta] * [\alpha]$ .

## Summary of important results

- Manifolds M with  $\pi_1(M) = 1$  are called *simply-connected*.
- π<sub>n</sub>(S<sup>n</sup>) = Z
   (the integer is known as the *degree* of the map and is related to the number of pre-images)
- π<sub>n</sub>(S<sup>d</sup>) = 1 for 1 ≤ n < d (contractible, not onto)
- $\pi_{n+1}(S^n) = \mathbb{Z}_2$ , for  $n \geq 3$ , but  $\pi_3(S^2) = \mathbb{Z}$  (related to Hopf bundle)
- π<sub>n+2</sub>(S<sup>2</sup>) = Z<sub>2</sub> for n ≥ 2. (Homotopy groups of spheres really are complicated!)
- Spectral sequences are an important tool: Let G be a Lie group with subgroup H then

 $\cdots \to \pi_n(H) \to \pi_n(G) \to \pi_n(G/H) \to \pi_{n-1}(H) \to \pi_{n-1}(G) \to \pi_{n-1}(G/H) \to \ldots$ 

is a long exact sequence. (example:  $G = S^3$ ,  $H = S^1$ ,  $G/H = S^2$ )

## Homotopy groups and Field Theory

- Why are these homotopy groups important for field theories?
- Field configurations are maps  $\phi : \mathbb{R}^d \to M$ , from flat space to a target space.
- Homotopies of maps occur naturally (e.g. time evolution is continuous and connects different field configurations in the same homotopy class).
- Two scenarios naturally give rise to homotopy groups. Both arise from boundary conditions (due to finite energy).
  - One-point compactification: There is a unique vacuum v<sub>0</sub> ∈ M, namely, φ(**x**) = v<sub>0</sub> for **x** → ∞. So, we can identify all these points, so that topologically ℝ<sup>d</sup> ∪ {∞} = S<sup>d</sup>. So, we need

$$\pi_d(M).$$

② Nontrivial maps at infinity: The vacuum is degenerate and forms a submanifold N of M. Then, in the limit |x| → ∞ there is a continuous map φ|<sub>∞</sub> : S<sup>d-1</sup><sub>∞</sub> → N. So, we need

$$\pi_{d-1}(N).$$

$\pi_n(S^k)$	ungauged	gauged	
$egin{array}{l} \pi_1(S^1) \ \pi_2(S^2) \ \pi_3(S^3) \ \pi_3(S^2) \end{array}$	Kinks Baby-Skyrmions, Lumps Skyrmions Hopf Solitons	Vortices Monopoles Instantons	

## Ginzburg-Landau vortices

• The Ginzburg-Landau energy is given by

$$V = \frac{1}{2} \int \left( B^2 + \overline{D_i \phi} D_i \phi + \frac{\lambda}{4} \left( 1 - \overline{\phi} \phi \right)^2 \right) d^2 x.$$

where  $\mathbf{x} = (x, y)$ .

• This is invariant under

$$\begin{aligned} \phi(\mathbf{x}) &\mapsto e^{i\alpha(\mathbf{x})}\phi(\mathbf{x}) \\ a_i(\mathbf{x}) &\mapsto a_i(\mathbf{x}) + \partial_i\alpha(\mathbf{x}). \end{aligned}$$

where  $e^{i\alpha(\mathbf{x})}$  is a spatially varying phase.

• Here  $D_i = \partial_i \phi - i a_i \phi$  is the covariant derivative and

$$B = \partial_1 a_2 - \partial_2 a_1$$

is the magnetic field.

• The vacuum is  $\phi = 1$ ,  $a_i = 0$  and gauge transformations of this.

• Asymptotically, for finite energy fields, we can fix the gauge so that

 $\lim_{\rho\to\infty}\phi(\rho,\theta)$ 

exists and varies continuously with  $\theta$ , where  $(x, y) = (\rho \cos \theta, \rho \sin \theta)$ . • Since  $|\phi| \to 1$  as  $\rho \to \infty$ ,

$$\lim_{\rho\to\infty}(\rho,\theta)=e^{i\alpha(\theta)},$$

where  $\alpha$  is a continuous function of  $\theta.$ 

- Winding number N: As θ increases from 0 to 2π, α(θ) increases by 2πN (φ is single valued). N is an arbitrary integer, cannot change under smooth deformations of the field, remains constant in time.
- *N* is also invariant under smooth gauge transformations.

## Topological charge II

• In polar coordinates  $(\rho, \theta)$ 

$$V = \frac{1}{2} \int_{0}^{\infty} \int_{0}^{2\pi} \left( B^2 + \overline{D_{\rho}\phi} D_{\rho}\phi + \frac{1}{\rho^2} \overline{D_{\theta}\phi} D_{\theta}\phi + \frac{\lambda}{4} \left( 1 - \overline{\phi}\phi \right)^2 \right) \rho \, \mathrm{d}\rho \, \mathrm{d}\theta.$$

• By Stokes theorem

$$\int_{\mathbb{R}^2} B \, \mathrm{d}^2 x = \int_0^{2\pi} a_\theta \, \mathrm{d}\theta \Bigg|_{\rho \to \infty}$$

• As  $\rho \to \infty$ , the covariant derivative  $D_{\theta}\phi = \partial_{\theta} - ia_{\theta}\phi$  has to vanish. Since  $\phi = e^{i\alpha(\theta)}$  we have  $a_{\theta} = \frac{d\alpha}{d\theta}$ . Hence

$$\int_{\mathbb{R}^2} B \, \mathrm{d}^2 x = \alpha(2\pi) - \alpha(0) = 2\pi N.$$

so N measures the magnetic flux units in the plane.

## Topological charge III

- If φ has only isolated zeros, then the number of these (counted with multiplicity) is N.
- A zero of φ is said to have multiplicity k, if on a small cirlce enclosing the zero,
   - arg φ increases by 2πk. For simple zeros k = ±1.



#### Energy of N Ginzburg-Landau vortices

• Let  $E_N$  be the minimal energy V of N vortices.

 $\begin{array}{ll} \lambda < 1 & E_N < NE_1 & \text{the vortices attract (Type I)} \\ \lambda > 1 & E_N > NE_1 & \text{the vortices repel (Type II)} \\ \lambda = 1 & E_N = NE_1 & \text{no forces between static vortices} \end{array}$ 



## Vortices at critical coupling $\lambda = 1$

• By "completing the square" V can be written as

$$V = \frac{1}{2} \int \left( \left( B - \frac{1}{2} \left( 1 - \overline{\phi}\phi \right) \right)^2 + \left( \overline{D_1 \phi + i D_2 \phi} \right) \left( D_1 \phi + i D_2 \phi \right) + B \right) \mathrm{d}^2 x.$$

Recall that

$$\int B \, \mathrm{d}^2 x = 2\pi N, \quad \mathrm{so} \quad V \geq \pi N.$$

Bogomolny equations:

$$D_1\phi + iD_2\phi = 0$$
$$B - \frac{1}{2}(1 - \overline{\phi}\phi) = 0.$$

• These equations cannot be solved analytically. However, a lot is known about the solutions.

- For given topological charge *N*, the Bogomolny equations have a 2*N* dimensional manifold of static solutions, known as the *moduli space M*<sub>*N*</sub>. (Gauge equivalent solutions are identified.)
- All zeros of  $\phi$  have positive multiplicity (generically there are only simple zeros).
- A solution is completely determined by the locations of these zeros, which can be anywhere. N unordered points in  $\mathbb{R}^2$  require 2N coordinates.
- There are no static forces between vortices for λ = 1, however, there will be velocity dependent forces.

• The standard relativistic Lagrangian is

$$\mathcal{L} = rac{1}{2} \overline{D_\mu \phi} D^\mu \phi - rac{1}{4} f_{\mu 
u} f^{\mu 
u} - rac{\lambda}{8} \left( 1 - \overline{\phi} \phi 
ight)^2,$$

where  $x^{\mu} = (t, \mathbf{x})$ .

- In the following, we will often use complex coordinates z = x + iy.
- We can parametrize the moduli space for λ = 1 in terms of the vortex positions Z<sub>i</sub>. Assuming that Z<sub>i</sub> are time dependent gives rise to the reduced Lagrangian

$$L_{\rm red.} = \frac{1}{2} \sum_{r,s=1}^{N} \left( g_{rs} \dot{Z}_r \dot{Z}_s + g_{r\overline{s}} \dot{Z}_r \dot{\overline{Z}}_s + g_{\overline{rs}} \dot{\overline{Z}}_r \dot{\overline{Z}}_s \right) - V_{\rm red.},$$

where

$$V_{\mathrm{red.}} = rac{\lambda-1}{8} \int \left(1-\overline{\phi}\phi
ight)^2 \mathrm{d}^2 x.$$

#### Properties of the moduli space

• Setting  $h = \log |\phi|^2$  the Bogomolny equations imply

$$abla^2 h + 1 - e^h = 4\pi \sum_{r=1}^N \delta^2(z - Z_r).$$

- The  $\delta$  functions arise because *h* has logarithmic singularities at the zeros  $Z_r$  of  $\phi$ .
- Expanding h around the point  $Z_r$  gives

$$h(z, \bar{z}) = 2 \log |z - Z_r| + a_r + \frac{1}{2} \bar{b}_r(z - Z_r) + \frac{1}{2} b_r(\bar{z} - \bar{Z}_r) + \dots$$

After a long calculation

$$L_{\rm red.} = \frac{\pi}{2} \sum_{r,s=1}^{N} \left( \delta_{rs} + 2 \frac{\partial b_s}{\partial Z_r} \right) \dot{Z}_r \dot{\bar{Z}}_s - V_{\rm red.}$$

• The moduli space metric

$$g = \frac{\pi}{2} \sum_{r,s=1}^{N} \left( \delta_{rs} + 2 \frac{\partial b_s}{\partial Z_r} \right) dZ_r d\bar{Z}_s$$

is Kähler.

- This structure provides a lot of information about the metric, although it is only know implicitly.
- The moduli space approximation captures the dynamics of vortices, in particular right-angle scattering.

• The Schrödinger-Chern-Simons Lagrangian

$$\mathcal{L}_{SCS} = \frac{i}{2} \left( \overline{\phi} D_0 \phi - \phi \overline{D_0 \phi} \right) + B a_0 + e_1 a_2 - e_2 a_1 - a_0 - \frac{1}{2} B^2 - \frac{1}{2} \overline{D_i \phi} D_i \phi - \frac{\lambda}{8} \left( 1 - \overline{\phi} \phi \right)^2,$$

is a model for vortex dynamics in superconductors.

- This Lagrangian is gauge invariant and Galilean invariant.
- $\mathcal{L}_{SCS}$  give rise to first order vortex dynamics.
- For  $\lambda$  close to one, we can again use our moduli space  $M_N$  to approximate the dynamics of N vortices.

## Moduli approximation and the Kähler potential

• Now, the reduced Lagrangian is also first order

$$L_{\mathrm{red.}} = -\sum_{i=1}^{2N} \mathcal{A}_i(\mathbf{y}) \dot{y}_i - V_{\mathrm{red.}}(\mathbf{y}),$$

where  $\boldsymbol{y}$  are the coordinates on the moduli space and

$$V_{\mathrm{red.}} = rac{\lambda-1}{8} \int \left(1-\overline{\phi}\phi
ight)^2 \mathrm{d}^2 x.$$

- $\mathcal{A}$  is a gauge potential, and  $\mathcal{F} = d\mathcal{A}$  the corresponding field strength.
- The equations of motion are

$$\mathcal{F}_{ij}\dot{y}_j = -rac{\partial V_{\mathrm{red.}}}{\partial y_i}$$

• The field strength  ${\cal F}$  is

$$\mathcal{F} = -i\pi\sum_{r,s=1}^{N}\left(\delta_{rs} + 2rac{\partial b_s}{\partial Z_r}
ight) dZ_r \wedge dar{Z}_s$$

which is the Kähler form associated to the metric g on  $M_N$ .

## Moduli space approximation

- For λ close to 1, two vortices circle around each other anticlockwise.
- Moduli space approximation is in agreement with numerical simulation.



#### Vortices on various domains

• We can consider physical spaces with a different metric, e.g.

$$ds^2 = dt^2 - \Omega(x, y)(dx^2 + dy^2),$$

where  $\Omega$  is a Riemannian metric on a physical space X.

• Again we can "complete the square" and obtain the Bogomolny equations

$$egin{array}{rcl} D_1\phi+iD_2\phi&=&0\ B-rac{\Omega}{2}\left(1-\overline{\phi}\phi
ight)&=&0, \end{array}$$

where  $B = f_{12}$ .

The integral

$$c_1 = \frac{1}{2\pi} \int_X f = \frac{1}{2\pi} \int_X B \, \mathrm{d}^2 x$$

is an integer. This topological invariant is known as the first *Chern number*.

## Compact domains and the Bradlow limit

• We can integrate the second Bogomolny equation over X and obtain

$$2\int_X B \mathrm{d}^2 x + \int_X |\phi|^2 \Omega \mathrm{d}^2 x = \int_X \Omega \mathrm{d}^2 x.$$

• If X has a finite area A we obtain

$$4\pi N + \int_X |\phi^2| \Omega \, \mathrm{d}^2 x = A.$$

• This gives us the Bradlow limit

$$A \ge 4\pi N$$

in other words, a vortex needs at least an area of  $4\pi$ .

- At the Bradlow bound  $A = 4\pi N$  both equations can trivially be solved by  $\phi = 0$  and  $B = \frac{\Omega}{2}$ .
- For the torus  $T^2$  the moduli space metric has been calculated as an expansion around the Bradlow limit.

## Hyperbolic vortices

• Setting  $h = \log |\phi|^2$  we can again derive an equation for h:

$$\nabla^2 h + \Omega - \Omega e^h = 4\pi \sum_{r=1}^N \delta^2 (z - Z_r).$$

For hyperbolic space

$$ds^2 = \frac{8}{(1-|z|^2)^2} dz \ d\overline{z}$$

with |z| < 1, the equation can be transformed to Liouville's equation, which is integrable.

• In this case, the moduli space is known explicitly, and

$$\phi=\frac{1-|z|^2}{1-|f|^2}\frac{df}{dz}.$$

f(z) has the rather simple form

$$f(z) = \prod_{i=1}^{N+1} \left( \frac{z-c_i}{1-\overline{c}_i z} \right)$$

where  $|c_i| < 1$ . The positions of the vortices are the zeros of  $\frac{df}{dz}$  .

## Metric for Hyperbolic vortices

• In hyperbolic space, the metric is

$$g = \frac{\pi}{2} \sum_{r,s=1}^{N} \left( \Omega(Z_r) \delta_{rs} + 2 \frac{\partial b_s}{\partial Z_r} \right) dZ_r d\bar{Z}_s$$

but now we can calculate  $b_s$  for special cases.

• The metric for *n* vortices on a regular polygon with *m* vortices fixed at the origin is given by

$$ds^2 = rac{4\pi n^3 |lpha|^{2n-2} dlpha \ dar{lpha}}{\left(1 - |lpha|^{2n}
ight)^2} \left(1 + rac{2n\left(1 + |lpha|^{2n}
ight)}{\sqrt{(m+1)^2\left(1 - |lpha|^{2n}
ight)^2 + 4n^2 |lpha|^{2n}}}
ight)$$

for  $n \neq m+1$ , and by

$$ds^{2} = \frac{12\pi n^{3}|\alpha|^{2n-2}d\alpha \ d\bar{\alpha}}{\left(1-|\alpha|^{2n}\right)^{2}}$$

for m + 1 = n. The nontrivial zeros are at  $z = \alpha e^{2\pi i k/n}$  for  $k = 0, \ldots, n - 1$ .